

Application in Bio-Mathematics of Hypergeometrid Type

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Introduction

In recent research work, Ronghe [4] has determined the equations of Atmospheric pressure and half life period, making use of Fox's H-functions. We shall now here establish certain results involving generalized H-functions which lead in Bio-mathematics. This paper concludes with some interesting special cases for G-functions of the main results established herein. Meijer's G-functions of two variables introduced by Agarwal (I) was extended by the introduction of H-function of two variables by Mittal and Gupta (3). They have given the following notations to define the H-function of two variables as:

$$(1) \quad H_{p,q; (r,s); (k,l)}^{0,n; (m_1, n_1); (m_2, n_2)} \left[\begin{matrix} x & (a_1; A_1, \alpha_1)_{1p} \\ y & (c_j; C_j)_{1r} (e_j; E_j)_{1k} \\ & (b_j; B_j, \beta_j)_{1q} \\ & (d_1, D_1)_{1s} (f_j, F_j)_{1l} \end{matrix} \right]$$

$$= -\frac{1}{4\pi} \int_{L_1} \int_{L_2} \theta(\xi, \eta) g(\xi) h(\eta) x^\xi y^\eta d\xi d\eta,$$

where,

$$g(\xi, \eta) = \frac{\prod_{j=1}^n \Gamma(1 - a_j + A_j \xi + \alpha_j \eta)}{\prod_{j=m}^n \Gamma(1 - b_j + B_j \xi + \beta_j \eta) \prod_{j=n+1}^n \Gamma(a_j - A_j \xi - \alpha_j \eta)}$$

$$g(\xi) = \frac{\prod_{j=1}^{m_1} \Gamma(d_j - D_j \xi) \prod_{j=1}^{n_1} \Gamma(1 - e_j + C_j \xi)}{\prod_{j=m_1+1}^s \Gamma(1 - d_j + D_j \xi) \prod_{j=n_1+1}^k \Gamma(e_j - C_j \xi)},$$

$$h(\eta) = \frac{\prod_{j=1}^{m_2} \Gamma(f_j - F_j \eta) \prod_{j=1}^{n_2} (1 - e_j + E_j \eta)}{\prod_{j=m_2+1}^{m_1} \Gamma(1 - f_j + F_j \eta) \prod_{j=n_2+1}^k \Gamma(e_j - E_j \eta)} \text{ valid for}$$

- (i) $|x| < 1, |y| < 1, 0 \leq n \leq p, 0 \leq m_1 \leq g, 0 \leq n_1 \leq s, 0 \leq m_2 \leq k, 0 \leq n_2 \leq 1.$
- (ii) All $A'S, B'S, C'S, D'S, E'S, F'S, \alpha's$ and $\beta'S$ are positive quantities.
- (iii) The H-function 1.1(1) converges provided

$$(a) U = - \sum_{j=n+1}^p A_j - \sum_{j=1}^q B_j + \sum_{j=1}^{m_1} D_j - \sum_{j=m_1+1}^s D_j + \sum_{j=1}^{n_1} C_j - \sum_{j=n_1+1}^r C_j > 0$$

$$(b) V = - \sum_{j=n+1}^p d_j - \sum_{j=1}^q \beta_j + \sum_{j=1}^{m_2} F_j - \sum_{j=m_2+1}^1 F_j + \sum_{j=1}^{n_2} E_j - \sum_{j=n_2+1}^k E_j > 0$$

$$(c) |\arg x| < \frac{1}{2} \pi U,$$

$$(d) |\arg y| < \frac{1}{2} \pi V$$

1.2. In this section we shall determine the Equation of Population Growth involving H-function of two variables.

Suppose that $P(t)$ is the Population size at time t and δP the growth in the Population corresponding to time δt , then we have

(1) $\delta P \propto P \delta t$, which gives the differential equation

(2) $DP/dt = \lambda P$,

where λ is proportional constant.

Integration of 1.2(2) yields.

$$\int \frac{dp}{p} = \lambda p + k_1, \text{ where } k_1 \text{ is a constant of integration and therefore}$$

$$(3) \int \frac{\Gamma(P)}{\Gamma(P+1)} dP = \lambda \frac{\Gamma(t+1)}{\Gamma(t)} + k_1$$

We can now determine the value of constant k_1 at the initial conditions $t = 0$.

$P = P_0$. When time increases, the population also increases. If we make

$P \rightarrow P + P_1 \xi$ and $t \rightarrow t + t_1 \xi$, then 1.2(3) gives

$$(4) \int \frac{\Gamma(P + P_1 \xi)}{\Gamma(1 + P + P_1 \xi)} dP = \lambda \frac{\Gamma(1 + t + t_1 \xi)}{\Gamma(t + t_1 \xi)} + k_1$$

Similarly, we can deduce.

$$(5) \int \frac{\Gamma(Q + Q_1 \eta)}{\Gamma(1 + Q + Q_1 \eta)} dQ = \lambda_1 \frac{\Gamma(1 + t^1 + t_1^1 \eta)}{\Gamma(t^1 + t_1^1 \eta)} + k_2$$

Combine 1.2(4) and 1.2(5) and multiply both sides of it by

$\frac{1}{(2\pi i)^2} \Phi(\xi, \eta) g(\xi) h(\eta)$, further, integrate with respect to ξ and η along the direction of double contours L_1 and L_2 and use 1.1(1) to obtain the following equation of population growth involving H-function of two variables :

$$\begin{aligned}
 (6) \quad & \iint H_{p,q}^{0,n} \left[\begin{matrix} (m_1+1, n_1+1); (m_2+1, n_2+1) \\ (r+1, s+1); (k+1, l+1) \end{matrix} \right] \left[\begin{matrix} x \\ y \end{matrix} \right] \left[\begin{matrix} (a_p; A_p, \alpha_p) \\ (1-P, P_1); (c_r, C_r); (1-Q, Q_1), (c_k, E_r) \\ (b_q; B_q, \beta_q) \\ (d_s, D_s), (-P, P_1); (f_1, F_1), (-Q, Q_1) \end{matrix} \right] dP dQ \\
 &= \mu_1 H_{p,q}^{0,n} \left[\begin{matrix} (m_1+1, n_1+1); (m_2+1, n_2+1) \\ (r+1, s+1); (k+1, l+1) \end{matrix} \right] \left[\begin{matrix} x \\ y \end{matrix} \right] \left[\begin{matrix} (a_p; A_p, \alpha_p) \\ (-t, t_1); (c_r, C_r); (-t^1, t_1^1), (e_k, E_k) \\ (b_q; B_q, \beta_q) \\ (d_s, D_s), (1-t_1); (f_1, f_1), (1-t^1, t_1^1) \end{matrix} \right] \\
 &+ \mu_2 H_{p,q}^{0,n} \left[\begin{matrix} (m_1+1, n_1+1); (m_2, n_2) \\ (r+1, s+1); (k, l) \end{matrix} \right] \left[\begin{matrix} x \\ y \end{matrix} \right] \left[\begin{matrix} (a_p; A_p, \alpha_p) \\ (-t, t_1); (c_r, C_r); (e_k, E_k) \\ (b_q; B_q, \beta_q) \\ (d_s, D_s), (1-t, t_1); (f_1, F_1) \end{matrix} \right] \\
 &+ \mu_3 H_{p,q}^{0,n} \left[\begin{matrix} (m_1, n_1); (m_2+1, n_2+1) \\ (r, s); (k+1, l+1) \end{matrix} \right] \left[\begin{matrix} x \\ y \end{matrix} \right] \left[\begin{matrix} (a_p; A_p, \alpha_p) \\ (c_r, C_r); (-t^1, t_1), (e_k, E_k) \\ (b_q; B_q, \beta_q) \\ (d_s, D_s); (f_1, F_1), (1-t^1, t_1^1) \end{matrix} \right] \\
 &+ \mu_4 H_{p,q}^{0,n} \left[\begin{matrix} (m_1, n_1); (m_2, n_2) \\ (r, s); (k+1) \end{matrix} \right] \left[\begin{matrix} x \\ y \end{matrix} \right] \left[\begin{matrix} (a_p; A_p, \alpha_p) \\ (c_r, C_r); (e_k, E_k) \\ (b_q; B_q, \beta_q) \\ (d_s, D_s); (f_1, F_1) \end{matrix} \right]
 \end{aligned}$$

where

(i) $\mu_1 (= \lambda \lambda_1), \mu_2 (= \lambda k_2), \mu_3 (= \lambda k_1)$

and $\mu_4 (= k_1 k_2)$ are all constants

(ii) $P_1 > 0, Q_1 > 0, t_1 > 0$ and $t_1^1 > 0$.

1.3. Special Cases:

If we put $A_j = \alpha_j = 1, (j=1,2, \dots, p), B_j = \beta_j = 1 (j=1,2, \dots, q),$

$C_j = 1 (j=1,2, \dots, r), D_j = 1 (j=1,2, \dots, s), E_j = 1 (j=1,2, \dots, k),$

$F_j = 1$ ($j=1,2, \dots, D$), $P_1 = 1$, $Q_1 = 1$, $t_1 = 1$ and $t_1' = 1$ in 1.2(6), then we have

$$\begin{aligned}
 (1) \quad & \iint G \left[\begin{matrix} n, n_1+1, n_2+1, m_1+1, m_2+1 \\ p(r+1, k+1), q, (s+1; 1+1) \end{matrix} \middle| \begin{matrix} x & (a_p) \\ y & (1-P), (c_r); (1-Q), (e_k) \\ & (b_q) \\ & (d_s), (-P); (f_1), (-Q) \end{matrix} \right] dP dQ \\
 &= \mu_1 G \left[\begin{matrix} n, n_1+1, n_2+1, m_1+1, m_2+1 \\ p(r+1; k+1), q, (s+1; 1+1) \end{matrix} \middle| \begin{matrix} x & (a_p) \\ y & (-t), (c_r); (-t^1), (e_k) \\ & (b_q) \\ & (d_s), (1-t); (f_1), (1-t^1) \end{matrix} \right] \\
 &+ \mu_2 G \left[\begin{matrix} n, n_1+1, n_2, m_1+1, m_2 \\ p, (r+1; k), q, (s+1; 1) \end{matrix} \middle| \begin{matrix} x & (a_p) \\ y & (-t), (c_r); (e_k) \\ & (b_q) \\ & (d_s), (1-t); (f_1) \end{matrix} \right] \\
 &+ \mu_3 G \left[\begin{matrix} n, n_1, n_2+1, m_1, m_2+1 \\ p, (r; k+1), q, (s: 1+1) \end{matrix} \middle| \begin{matrix} x & (a_p) \\ y & (c_r); (-t^1), (e_k) \\ & (b_q) \\ & (d_s), (f_1), (1-t^1) \end{matrix} \right] \\
 &+ \mu_4 G \left[\begin{matrix} n, n_1, n_2, m_1, m_2 \\ p, (r; k), q, (s: 1) \end{matrix} \middle| \begin{matrix} x & (a_p) \\ y & (c_r); (e_k) \\ & (b_q) \\ & (d_s); (f^1) \end{matrix} \right]
 \end{aligned}$$

where μ_1, μ_2, μ_3 and μ_4 are all constants and the G-functions of two variables in 1.3(1) are valid for

$$|x| < 1, |y| < 1,$$

$0 \leq n \leq p, 0 \leq n_1 \leq r, 0 \leq n_2 \leq k, 0 \leq m_1 \leq s, 0 \leq m_2 \leq 1, 0 \leq q$ and for convergence, we have

$$p + q + s + r < 2(m_1 + n_1 + n)$$

$$p + q + 1 + k < 2(m_2 + n_2 + n)$$

$$|\arg x| < \pi [m_1 + n_1 + n - (p + q + s + r) / 2]$$

$$|\arg x| < \pi [m_2 + n_2 + n - (p + q + 1 + k) / 2]$$

In particular, if we take $p = 0$ and $q = 0$ in 1.3(1) we have.

$$\begin{aligned}
 (2) \quad & \iint G_{r+1, s+1}^{m_1+1, n_1+1} \left[x \left| \begin{matrix} (1-p), (C_r) \\ (d_s), (-P) \end{matrix} \right. \right] \times G_{k+1, 1, +1}^{m_2+1, n_2+1} \left[y \left| \begin{matrix} (1-Q), (e_k) \\ (f_1), (-Q) \end{matrix} \right. \right] dPdQ \\
 &= \mu_1 G_{r+1, s+1}^{m_1+1, n_2+1} \left[x \left| \begin{matrix} (-t), (e_r) \\ (d_s), (1-t) \end{matrix} \right. \right] \times G_{k+1, 1, +1}^{m_2+1, n_2+1} \left[y \left| \begin{matrix} (-t^1), (e_k) \\ (f_1), (1-t^1) \end{matrix} \right. \right] \\
 &+ \mu_2 G_{r+1, s+1}^{m_1+1, n_1+1} \left[x \left| \begin{matrix} (-t), (e_r) \\ (d_s), (1-t) \end{matrix} \right. \right] \times G_{k, 1}^{m_2, n_2} \left[y \left| \begin{matrix} (e_k) \\ (f_1) \end{matrix} \right. \right] \\
 &+ \mu_3 G_{r, s}^{m_1, n_1} \left[x \left| \begin{matrix} (e_r) \\ (d_s) \end{matrix} \right. \right] \times G_{k+1, 1, +1}^{m_2+1, n_2+1} \left[y \left| \begin{matrix} (-t^1), (e_k) \\ (f_1), (1-t^1) \end{matrix} \right. \right] \\
 &+ \mu_3 G_{r, s}^{m_1, n_1} \left[x \left| \begin{matrix} (e_r) \\ (d_s) \end{matrix} \right. \right] \times G_{k, 1}^{m_2, n_2} \left[y \left| \begin{matrix} (e_k) \\ (f_1) \end{matrix} \right. \right].
 \end{aligned}$$

where μ_1, μ_2, μ_3 and μ_4 are all constants and the G-functions in 1.3 (2) are valid for $|x| < 1, |y| < 1,$

$$\begin{aligned}
 &0 \leq m_1 \leq s, 0 \leq m_1 \leq r, 0 \leq m_2 \leq 1, 0 \leq n_2 \leq k \\
 &r + s < 2(m_1 + n_1) \\
 &k + 1 < 2(m_2 + n_2) \\
 &|\arg x| < \pi [m_1 + n_1 - (r + s) / 2], \\
 &|\arg y| < \pi [m_2 + n_2 - (k + 1) / 2]
 \end{aligned}$$

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